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Feb. 20th, 2020, Duisburg, Germany




Simulation of Quasi- Static Electric and Magnetic Signatures of Naval Vessels

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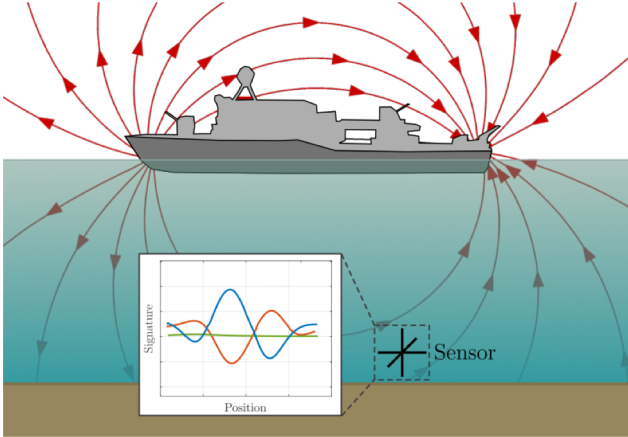
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Motivation

Why simulate the signatures of naval vessels ?



- Signatures can be subdivided in **electric**, **magnetic**, acoustic and pressure
- Signatures exploitable by underwater sensors (e.g. naval mines)
- Amplitude and shape of signatures contain information about the vessel (e.g. size, type, ...)
- Signature can be used as trigger criterion for naval mines


➡ Knowing signatures minimizes detection risk !

- 2/13 -

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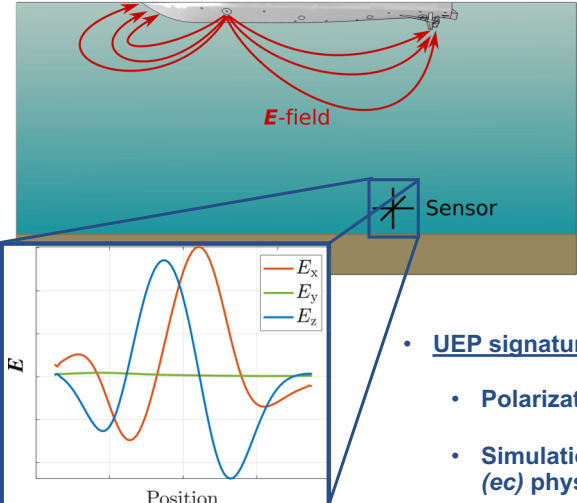
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Signatures of Naval Vessels

Underwater Electric Potential (UEP)




- **Generated by:**
 - corrosion process of the metallic materials of the vessel
 - Corrosion protection (CP) system
- UEP signature represented by an electric field E
- **UEP signature highly nonlinear:**
 - Polarization data necessary
 - Simulation possible using e.g. *Electric Currents (ec)* physics

- 3/13 -

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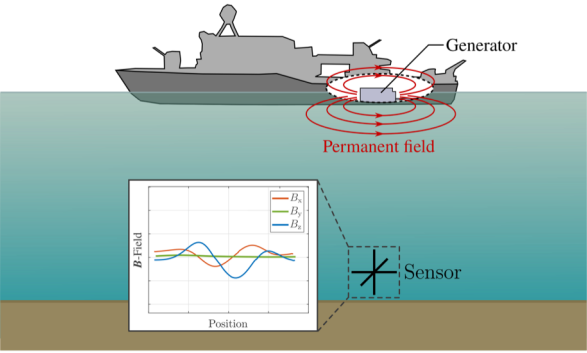
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Signatures of Naval Vessels

Magnetic signatures



- **Generated by:**
 - Presence of the vessel in the earth's magnetic field (static and quasi-static)
 - Onboard generators / motors
 - Corrosion protection (CP) system

Magnetic signatures also time-dependent / transient


- Simulation possible using e.g. *Magnetic Fields (mf)* physics
- Using time-dependent study to account for transient effects

- 4/13 -

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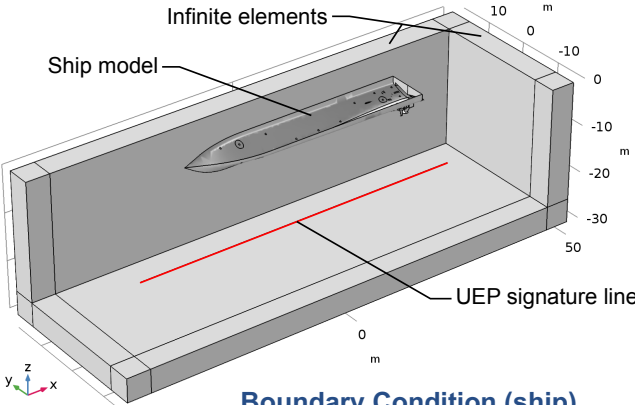
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Simulation Setup

Computational domain for UEP signature



Boundary Condition (ship)

- Inward current density $J_{n,inward} = -n \cdot J$
- $J_{n,inward} = f(\varphi)$

Stationary Equations (ec)

- $\nabla \cdot J = Q_j$
- $J = \sigma E + J_e$
- $E = -\nabla V$

Solver and DoF


- Stationary evaluation
- Direct solver (PARDISO)
- DoF approx. 450000

- 5/13 -

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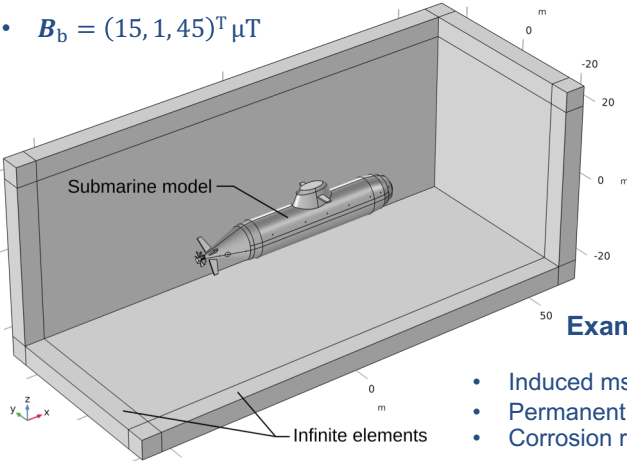


Simulation Setup

Computational domain for magnetic signatures

Background field

- $B_b = (15, 1, 45)^T \mu T$



Example magnetic signatures (ms)

- Induced ms
- Permanent ms
- Corrosion related ms
- Eddy current ms
- Disturbance ms
- ...

Stationary equations (mf)

- $\nabla \times H = J$
- $B = \nabla \times (A_b + A_r)$
- $J = \sigma E + J_e$

and time dependent (mf)


- $E = -\frac{\partial}{\partial t} (A_b + A_r)$

- 6/13 -

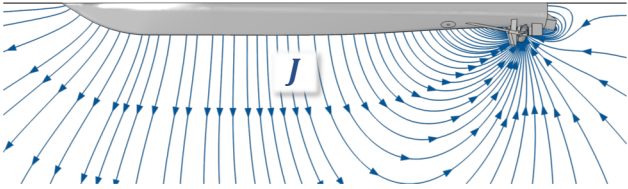
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Simulation Results – UEP



- UEP related current density J pointing from hull (distributed anode) to propellers (cathodes)
- Different material combinations can be examined

- Electric potential distribution "on hull" can be visualized (hull protected or unprotected)
- Necessary electric currents for cathodic protection (CP) analyzable




Helpful in both estimating the UEP signature and designing the CP system

– 7/13 –

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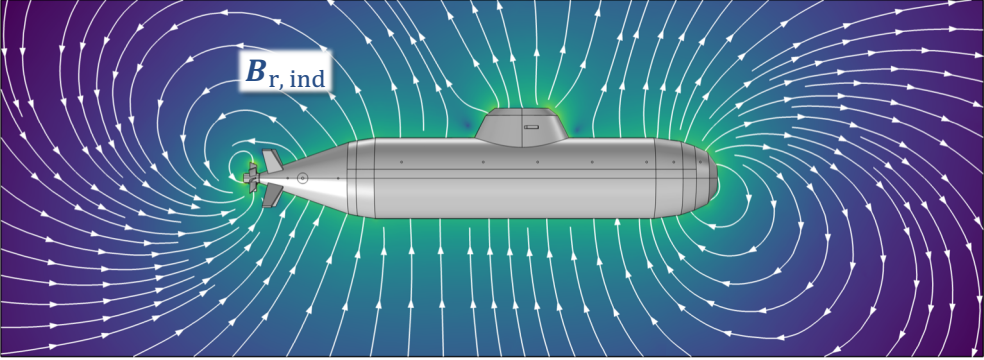
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Simulation Results – Magnetic signatures

Induced magnetic fields

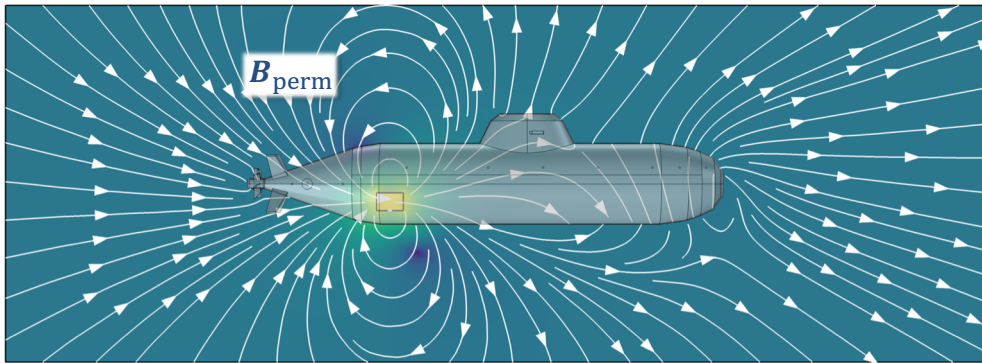


- Influence of magnetized hull can be evaluated for various material combinations
- Crucial for magnetic silencing (degaussing)

– 8/13 –

Simulation Results – Magnetic signatures

Permanent magnetic fields

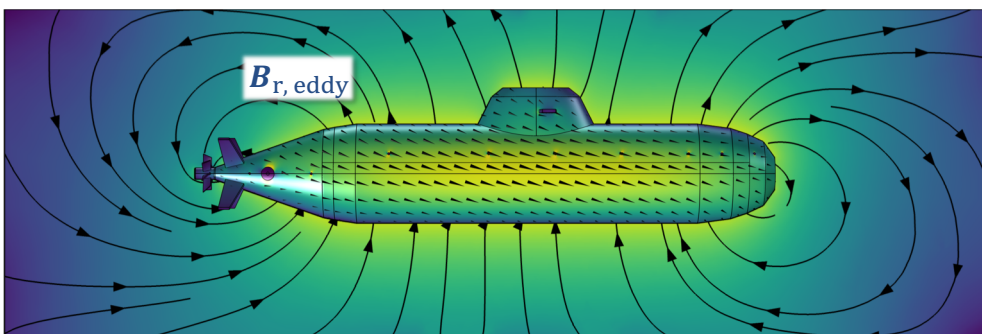


- Impact of onboard sources can be examined which additionally generate disturbances in the earth's magnetic field
- Crucial for magnetic silencing (degaussing)

– 9/13 –

Simulation Results – Magnetic signatures

Eddy current magnetic fields




- Eddy current magnetic field is one of the most important magnetic signatures
- Still on-going research regarding real-time control for eddy current field compensation

– 10/13 –

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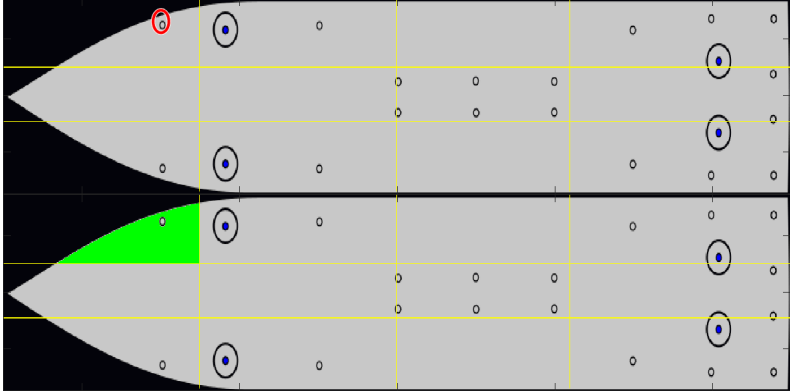
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Additional research

Cathodic protection and artificial neural networks (ANN)




- Using Comsol and LiveLink for Matlab to predict sector of coating damage with approx. 90 % accuracy

- 11/13 -

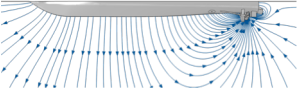

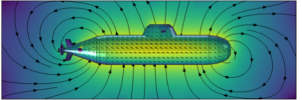
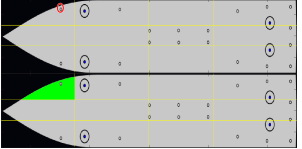
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Conclusion & Outlook

- Electrochemical behavior for corrosion of hull and UEP signature can be simulated 
- Estimation of cathodic protection design 
- Evaluation of magnetic signatures possible in both stationary and time-dependent manner 
- Combination with LiveLink for Matlab allows for new concepts (e.g. coating damage evaluation) 

- 12/13 -

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<p>Thank you for your attention!</p> <p>Questions?</p>		
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