## Point-missing s-resolvable t-designs: Infinite series of 4-designs with constant index

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#### Abstract

The paper deals with t-designs that can be partitioned into s-designs, each missing a point of the underlying set, called point-missing s-resolvable t-designs, with emphasis on their applications in constructing t-designs. The problem considered may be viewed as a generalization of overlarge sets which are defined as a partition of all the  $\binom{v+1}{k}$  k-sets chosen from a (v + 1)-set X into (v + 1) mutually disjoint s- $(v, k, \delta)$  designs, each missing a different point of X. Among others, it is shown that the existence of a point-missing (t - 1)-resolvable t- $(v, k, \lambda)$  design leads to the existence of a t- $(v, k + 1, \lambda')$  design. As a result, we derive various infinite series of 4-designs with constant index using overlarge sets of disjoint Steiner quadruple systems. These have parameters 4- $(3^n, 5, 5)$ , 4- $(3^n + 2, 5, 5)$  and 4- $(2^n + 1, 5, 5)$ , for  $n \geq 2$ , and were unknown until now. We also include a recursive construction of point-missing s-resolvable t-designs and its application.

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#### 1 Introduction

The paper is concerned with point-missing s-resolutions of t-designs and applications thereof. In general, a partition of a t- $(v, k, \lambda)$  design  $(X, \mathcal{B})$  into mutually disjoint s- $(w, k, \delta)$  designs,  $w \leq v$ , s < t, is termed an s-resolution. If w = v, then  $(X, \mathcal{B})$  is called s-resolvable; in particular, if  $(X, \mathcal{B})$  is the complete k-(v, k, 1) design, then an sresolution of  $(X, \mathcal{B})$  is called a *large set* of s-designs. If w = v - 1, then  $(X, \mathcal{B})$  is called point-missing s-resolvable. A point-missing s-resolution of the complete k-(v, k, 1)design is called an *overlarge set* of s-designs. Point-missing s-resolvability remains still sparsely investigated; however, several computational and theoretical works on the subject can be found in the literature [9, 13, 15, 16, 19, 20, 23]. Point-missing s-resolvability is complementarily related to what we call pencil-like s-resolvability for t-designs, and vice versa. As far as we know the first example of infinite series of nontrivial point-missing s-resolvable t-designs for  $t \ge 4$  can be found in a paper of Alltop in 1972 [2], in which the author constructed a series of  $4 \cdot (2^n + 1, 2^{n-1}, (2^{n-1} - 3)(2^{n-2} - 1))$  designs for  $n \ge 4$  as the union of  $2^n + 1$  mutually disjoint  $3 \cdot (2^n, 2^{n-1}, 2^{n-2} - 1)$  designs. We prove theorems for constructing new t-designs from point-missing and pencil-like s-resolvable t-designs. By using these theorems for overlarge sets of disjoint Steiner quadruple systems with  $v = 3^n - 1$  and  $v = 3^n + 1$  points constructed by Teirlinck [23], including the already known case with  $v = 2^n$ , we derive various infinite series of  $4 \cdot (v+1, 5, 5)$  designs, which were unknown until now. It is worthy of note that no large sets of Steiner quadruple systems are constructed to date; however, large sets of Steiner 2-designs for k = 4 with v = 13, 16 points are known to exist [10, 12, 14]. We also show a recursive construction of point-missing s-resolvable t-designs and its application.

For the sake of clarity we include a few basic definitions. A t-design, denoted by  $t \cdot (v, k, \lambda)$ , is a pair  $(X, \mathcal{B})$ , where X is a v-set of points and  $\mathcal{B}$  is a collection of k-subsets of X, called blocks, such that every t-subset of X is a subset of exactly  $\lambda$ blocks, and  $\lambda$  is called the *index* of the design. A t-design is called *simple* if no two blocks are identical, otherwise, it is called *non-simple*. A  $t \cdot (v, k, 1)$  design is called a Steiner t-design. For any point  $x \in X$ , let  $\mathcal{B}_x = \{B \setminus \{x\} : x \in B \in \mathcal{B}\}$ . Then  $(X \setminus \{x\}, \mathcal{B}_x)$  is a  $(t-1) \cdot (v-1, k-1, \lambda)$  design, called a derived design of  $(X, \mathcal{B})$ . It can be shown by simple counting that a  $t \cdot (v, k, \lambda)$  design is an  $s \cdot (v, k, \lambda_s)$  design for  $0 \leq s \leq t$ , where  $\lambda_s = \lambda {v-s \choose t-s} / {k-s \choose t-s}$ . Since  $\lambda_s$  is an integer, necessary conditions for the parameters of a t-design are  ${k-s \choose t-s} \mid \lambda {v-s \choose t-s}$  for  $0 \leq s \leq t$ . The smallest positive integer  $\lambda$  for which these necessary conditions are satisfied is denoted by  $\lambda_{\min}(t, k, v)$ or simply  $\lambda_{\min}$ . If  $\mathcal{B}$  is the set of all k-subsets of X, then  $(X, \mathcal{B})$  is a  $t \cdot (v, k, \lambda_{\max})$ design, called the *complete* design, where  $\lambda_{\max} = {v-t \choose k-t}$ . If we take  $\delta$  copies of the complete design, we obtain a  $t \cdot (v, k, \delta {v-t \choose k-t})$  design, which is refered to as a *trivial* t-design; otherwise, it is called a *non-trivial* t-design.

### 2 Point-missing s-resolvable t-designs

A t- $(v, k, \lambda)$  design  $(X, \mathcal{B})$  is said to be *s*-resolvable, for 0 < s < t, if its block set  $\mathcal{B}$  can be partitioned into  $N \ge 2$  classes  $\mathcal{B}_1, \ldots, \mathcal{B}_N$  such that each  $(X, \mathcal{B}_i)$  is an s- $(v, k, \delta)$ design for  $i = 1, \ldots, N$ . Such a partition is called an *s*-resolution of  $(X, \mathcal{B})$  and each  $\mathcal{B}_i$  is called an *s*-resolution class or simply a resolution class, see e.g. [25, 26].

If the complete k-(v, k, 1) design can be partitioned into N disjoint t- $(v, k, \lambda)$  designs, where  $N = \binom{v-t}{k-t}/\lambda$ , then we say that there exists a *large set* of t-designs denoted by LS[N](t, k, v) or by  $LS_{\lambda}(t, k, v)$  to emphasize the value  $\lambda$ .

In the most general form, the concept of point-missing s-resolvability of a t- $(v, k, \lambda)$  design can be defined as follows.

**Definition 2.1** Let  $(X, \mathcal{B})$  be a t- $(v, k, \lambda)$  design and let  $1 \leq s \leq t - 1$ .  $(X, \mathcal{B})$  is called point-missing s-resolvable, if the block set  $\mathcal{B}$  can be partitioned into mutually disjoint s- $(v - 1, k, \delta)$  designs, each missing a point of X.

However, Definition 2.1 is equivalent to a definition that describes point-missing resolutions with more exact details. We now give an explanation.

Let  $X = \{x_1, \ldots, x_v\}$  and let  $X_i = X \setminus \{x_i\}, i = 1, \ldots, v$ . Let  $m_i$  denote the number of  $s \cdot (v - 1, k, \delta)$  designs  $(X_i, \mathcal{B}_i)$  missing  $x_i$  in the resolution. First we show that any  $x_i \in X$  is a missing point of an s-design  $(X_i, \mathcal{B}_i)$ . More precisely, let  $Y \subseteq X$  be the subset of X such that there is no design  $(X_i, \mathcal{B}_i)$  missing point  $x_i$ , when  $x_i \in Y$ . Assume that  $Y \neq \emptyset$ . Then the blocks of  $\mathcal{B}$  can be written as follows.

$$\mathcal{B} = \bigcup_{x_h \in X \setminus Y} m_h \mathcal{B}_h, \text{ where } m_h \mathcal{B}_h := \underbrace{\mathcal{B}_h \cup \dots \cup \mathcal{B}_h}_{m_h \text{ times}}$$

Consider two given points  $x_i \in Y$  and  $x_j \in X \setminus Y$ . Since  $x_i \in Y$ , there is no s-design  $(X_i, \mathcal{B}_i)$  missing  $x_i$ . Thus  $x_i$  appears in each design  $(X_h, \mathcal{B}_h)$ , where  $x_h \in X \setminus Y$ , therefore  $x_i$  appears in  $\sum_{x_h \in X \setminus Y} m_h \delta_1$  times in the blocks of  $\mathcal{B}$ , where  $\delta_1 = \delta_{\binom{v-2}{k-1}}^{\binom{v-2}{k-1}}$ . Whereas the point  $x_j \in X \setminus Y$  appears in  $\sum_{x_h \in X \setminus \{Y \cup \{x_j\}\}} m_h \delta_1$  times in the blocks of  $\mathcal{B}$ , which is a contradiction if  $Y \neq \emptyset$ . Further, we show that  $m_1 = \cdots = m_v$ . W.l.o.g., assume by contradiction that  $m_1 \neq m_2$ . Then the number of blocks containing  $x_1$  (resp.  $x_2$ ) is then  $\sum_{x \in X \setminus \{x_1\}} m_x \delta_1 = m_2 \delta_1 + \sum_{i=3}^v m_i \delta_1$  (resp.  $\sum_{x \in X \setminus \{x_2\}} m_x \delta_1 = m_1 \delta_1 + \sum_{i=3}^v m_i \delta_1$ ). Since  $m_2 \delta_1 + \sum_{i=3}^v m_i \delta_1 = m_1 \delta_1 + \sum_{i=3}^v m_i \delta_1$ , we have  $m_2 \delta_1 = m_1 \delta_1$ , or equivalently  $m_2 = m_1$ , contradicting the assumption. Thus we must have  $m_1 = \cdots = m_v$ .

The discussion above suggests an equivalent formulation of Definition 2.1 as follows.

**Definition 2.2** Let  $(X, \mathcal{B})$  be a t- $(v, k, \lambda)$  design and let  $1 \leq s < t$  be an integer.  $(X, \mathcal{B})$  is said to be point-missing s-resolvable, if there is an integer  $m \geq 1$  such that the following hold.

- 1.  $\mathcal{B} = \mathcal{B}_{x_1} \cup \cdots \cup \mathcal{B}_{x_v}$ , where  $X = \{x_1, \ldots, x_v\}$ ,
- 2.  $\mathcal{B}_x = \mathcal{B}_x^1 \cup \cdots \cup \mathcal{B}_x^m$ , each  $(X \setminus \{x\}, \mathcal{B}_x^j)$  is an s- $(v-1, k, \delta)$  design,  $j = 1, \ldots, m$ , and m is called the multiplicity of the point x.

If m = 1,  $(X, \mathcal{B})$  is simply called point-missing s-resolvable. Moreover, if m > 1, then  $(X \setminus \{x\}, \mathcal{B}_x)$  is an  $s \cdot (v - 1, k, m\delta)$  design. Therefore,  $(X, \mathcal{B})$  again is a union of v mutually disjoint  $s \cdot (v - 1, k, m\delta)$  design, each missing a different point of X. Hence, in general, when we speak of point-missing s-resolvable t-designs we mean m = 1.

If the complete k-(v, k, 1) design can be partitioned into v mutually disjoint s- $(v-1, k, \delta)$  designs (i.e. point-missing *s*-resolvable), then we have an *overlarge set* of s- $(v-1, k, \delta)$  designs.

**Lemma 2.1** Let  $(X, \mathcal{B})$  be a point-missing s-resolvable t- $(v, k, \lambda)$  design and assume that each point in the resolution has multiplicity m. Then

$$\delta = \lambda \binom{v-s}{t-s} / \binom{k-s}{t-s} m(v-s).$$

In particular, if the complete t-(v, t, 1) design is point-missing (t - 1)-resolvable, then the designs in the resolution are Steiner (t - 1)-(v - 1, t, 1) designs.

*Proof.* By assumption, we have

$$\mathcal{B} = \bigcup_{x \in X} \{ \mathcal{B}^1_x \cup \dots \cup \mathcal{B}^m_x \}$$

where  $(X \setminus \{x\}, \mathcal{B}_x^i)$  is an s- $(v - 1, k, \delta)$  design. Let  $S = \{x_1, \ldots, x_s\} \subseteq X$ . Then S does not appear in any block of  $\mathcal{B}_{x_j}^i$ , for  $j = 1, \ldots, s$  and  $i = 1, \ldots, m$ . Further, S appears in each  $\mathcal{B}_{x_j}^i$  with  $j \neq 1, \ldots, s$ , exactly  $\delta$  times. Thus S appears  $m(v - s)\delta$  times in the blocks of  $\mathcal{B}$ . On the other hand, the number of blocks in  $\mathcal{B}$  containing S is  $\lambda_s = \frac{\binom{v-s}{t-s}}{\binom{k-s}{t-s}}\lambda$ . Therefore  $\lambda_s = m(v - s)\delta$  and thus  $\delta = \frac{\lambda_s}{m(v-s)}$ , as desired.  $\Box$ 

Recall that the complement of an s-resolvable t-design is again s-resolvable. However, it is not true with a point-missing s-resolvable t-design. Let  $X := \{x_1, \ldots, x_v\}$ and let  $X_i := X \setminus \{x_i\}, i = 1, \ldots, v$ . To simplify the typing we write: if  $Y \subseteq X$ , then  $\overline{Y} := X \setminus Y$ , whereas if  $Y \subseteq X_i$ , then  $\widetilde{Y} := X_i \setminus Y$ . Let  $(X, \mathcal{D})$  be a point-missing s-resolvable t-design with parameters  $t \cdot (v, k, \lambda)$  and let  $(X, \overline{\mathcal{D}})$  be its complement which has parameters  $t \cdot (v, v - k, \overline{\lambda})$ , where  $\overline{\lambda} = \lambda {\binom{v-k}{t}}/{\binom{k}{t}}$ . Let  $\mathcal{D} = \mathcal{D}_1 \cup \cdots \cup \mathcal{D}_v$ be a partition of  $\mathcal{D}$  into v point-missing s-resolution classes, where  $(X_i, \mathcal{D}_i)$  is an  $s \cdot (v - 1, k, \delta)$  design, for  $i = 1, \ldots, v$ . The complement of  $(X_i, \mathcal{D}_i)$  (within  $X_i$ ) is an  $s \cdot (v - 1, v - 1 - k, \widetilde{\delta})$  design  $(X_i, \widetilde{\mathcal{D}}_i)$  with  $\widetilde{\delta} = \delta {\binom{v-1-k}{s}}/{\binom{k}{s}}$ . So, we have  $\overline{\mathcal{D}} =$  $\overline{\mathcal{D}}_1 \cup \cdots \cup \overline{\mathcal{D}}_v = (\{x_1\} \cup \widetilde{\mathcal{D}}_1) \cup \cdots \cup (\{x_v\} \cup \widetilde{\mathcal{D}}_v)$ , where  $\{x_i\} \cup \widetilde{\mathcal{D}}_i = \{\{x_i\} \cup \widetilde{\mathcal{D}} \mid \widetilde{\mathcal{D}} \in \widetilde{\mathcal{D}}_i\}$ . Thus,  $\overline{\mathcal{D}}_i = (\{x_i\} \cup \widetilde{\mathcal{D}}_i)$  is not an s-design, but rather a "pencil". Hence, the decomposition of  $(X, \overline{\mathcal{D}})$  suggests the following definition.

**Definition 2.3** Let  $X = \{x_1, \ldots, x_v\}$  and denote  $X_i := X \setminus \{x_i\}, i = 1, \ldots, v$ . Let  $(X, \mathcal{B})$  be a t- $(v, k, \lambda)$  design. If for some  $x_i \in X$  there exists an s- $(v - 1, k - 1, \delta)$  design  $(X_i, \mathcal{B}_i)$  for  $1 \leq s < t$ , then we call  $\{x_i\} \cup \mathcal{B}_i = \{\{x_i\} \cup \widetilde{\mathcal{B}} \mid \widetilde{\mathcal{B}} \in \widetilde{\mathcal{B}}_i\} \subseteq \widetilde{\mathcal{B}}$  an s-pencil of  $(X, \mathcal{B})$ . If  $\mathcal{B} = (\{x_1\} \cup \mathcal{B}_1) \cup \cdots \cup (\{x_v\} \cup \mathcal{B}_v)$ , where  $(X_i, \mathcal{B}_i)$  is an s- $(v - 1, k - 1, \delta)$  design, then  $(X, \mathcal{B})$  is said to be pencil-like s-resolvable.

As observed above, the complement of a point-missing s-resolvable t-design is a pencillike s-resolvable t-design. Conversely, it is straightfoward to check that the complement of a pencil-like s-resolvable t-design is a point-missing s-resolvable t-design. Hence the notion of point-missing s-resolvability and that of pencil-like s-resolvability are complementary equivalent. We record this fact in the following lemma.

**Lemma 2.2** A t-design is point-missing s-resolvable if and only if its complement is pencil-like s-resolvable.

The next theorem shows a relation between certain classes of t-designs and pointmissing (t-1)-resolvable t-designs, in terms of derived designs. **Theorem 2.3** Let  $(X, \mathcal{B})$  be a simple t- $(v, k, \lambda)$  design with  $|B \cap B'| \leq k - 2$  for any two distinct blocks  $B, B' \in \mathcal{B}$ . Then there exists a simple point-missing (t - 1)resolvable t- $(v, k - 1, (k - t)\lambda)$  design  $(X, \mathcal{D})$ . In particular, if  $(X, \mathcal{B})$  is a Steiner t-(v, t + 1, 1) design, then there exists an overlarge set of Steiner (t - 1)-(v - 1, t, 1)designs.

Proof. For a given point  $x \in X$  consider the derived design  $(X \setminus \{x\}, \mathcal{B}_x)$  at x with parameters (t-1)- $(v-1, k-1, \lambda)$ . Here  $\mathcal{B}_x = \{B \setminus \{x\} \mid x \in B, B \in \mathcal{B}\}$ . Define  $\mathcal{D} = \bigcup_{x \in X} \mathcal{B}_x$ . We claim that  $(X, \mathcal{D})$  is a t- $(v, k-1, (k-t)\lambda)$  design. Let  $T = \{x_1, \ldots, x_t\} \subseteq X$ . Then there are  $\lambda$  blocks of  $\mathcal{B}$ , say,  $B_1, \ldots, B_\lambda$  containing T. Each  $B_i, i = 1, \ldots, \lambda$ , gives rise to a set  $\mathbb{D}_i = \{D = B_i \setminus \{x\} \mid x \in B_i \setminus T\} \subseteq \mathcal{D}$  having (k-t) blocks D containing T. Thus there are  $(k-t)\lambda$  blocks  $D \in \mathcal{D}$  containing T in total, as desired. The simplicity of  $(X, \mathcal{D})$  is a consequence of the property:  $|B \cap B'| \leq k-2, B, B' \in \mathcal{B}, B \neq B'$ , which can be seen as follows. Let D, D' be two blocks of  $\mathcal{D}$ . If  $D, D' \in \mathcal{B}_x$  for some  $x \in X$ , then  $D \neq D'$ , since  $(X \setminus \{x\}, \mathcal{B}_x)$  is the derived design at x. If  $D \in \mathcal{B}_x$  and  $D' \in \mathcal{B}_y$  with  $x \neq y$ , then again  $D \neq D'$ . This is because if D = D', then the two blocks  $B = D \cup \{x\}$  and  $B' = D' \cup \{y\}$  of  $\mathcal{B}$  would have  $|B \cap B'| = k - 1$ , a contradiction. In addition, if  $(X, \mathcal{B})$  is a Steiner t-(v, t+1, 1) design, then  $(X, \mathcal{D})$  becomes the complete t-(v, t, 1) design. In other words, the set of v distinct (t-1)-(v-1,t,1) derived designs of  $(X, \mathcal{B})$  forms an overlarge set.  $\Box$ 

- **Remark 2.1** 1. The proof of Theorem 2.3 shows that the constructed  $t \cdot (v, k 1, (k-t)\lambda)$  design is not simple, if there are two blocks  $B, B' \in \mathcal{B}$  with  $|B \cap B'| = k 1$ .
  - 2. It should be stressed that the set of v distinct derived designs of a Steiner t-(v, k, 1) design with k > t + 1 in Theorem 2.3 will not form an overlarge set of (t 1)-(v 1, k 1, 1) designs, but rather a point-missing (t 1)-resolution of a t-(v, k 1, (k t)) design.

The following corollary is an immediate consequence of Theorem 2.3.

**Corollary 2.4** Assume that there exists a Steiner t-(v, k, 1) design. Then there exists a point-missing (t-1)-resolvable t-(v, k-1, k-t) design.

The case k = t+1 of Corollary 2.4 is known as examples of overlarge sets of Steiner designs, see [23]. Thus, if there exists a Steiner t-(v, t + 1, 1) design, then there exists a point-missing (t - 1)-resolvable t-(v, t, 1) design, i.e. an overlarge set of Steiner (t-1)-(v-1, t, 1) designs. Note that the converse of this statement is not true, i.e. if there exists an overlarge set of Steiner (t-1)-(v-1, t, 1) designs, it is not necessarily true that a Steiner t-(v, t + 1, 1) design exists. For example, Östergård and Pottonen [17] have shown that a Steiner 4-(17, 5, 1) design does not exist. Nevertheless, there exists an overlarge set of Steiner 3-(16, 4, 1) designs, see [23]. And crucially, Teirlinck [23] has shown that there are overlarge sets of Steiner 3-(v, 4, 1) designs for  $v = 3^n - 1$ ,  $n \ge 2$  and  $v = 3^n + 1$ ,  $n \ge 1$ , despite the fact that only a finite number of Steiner 4-(v, 5, 1) designs are hitherto known. The general case  $k \ge t + 2$  is interesting, since Theorem 2.3 provides a pointmissing (t-1)-resolvable t-(v, k - 1, k - t) design, which is not a complete design. Examples about this case can be seen, for instance, from Steiner 5-(24, 8, 1) and 5-(28, 7, 1) designs. Here we obtain point-missing 4-resolvable 5-(24, 7, 3) and 5-(28, 6, 2) designs, where designs in the resolution are Steiner 4-(23, 7, 1) and 4-(27, 6, 1) designs, respectively. Similarly, there are point-missing 3-resolvable 4-(23, 6, 3) and 4-(27, 5, 2) designs having Steiner 3-(22, 6, 1) and 3-(26, 5, 1) designs in the resolution, respectively.

As a further application of Theorem 2.3, we consider the infinite series of 4-(q+1, 6, 10) designs with  $q = 2^n$ ,  $n \ge 5$  and gcd(n, 6) = 1, [8], having the property that any two blocks of the designs intersect in at most 4 points. Thus we have the following result.

**Corollary 2.5** Let  $q = 2^n$ ,  $n \ge 5$  and gcd(n, 6) = 1. Then there exists a pointmissing 3-resolvable 4-(q+1, 5, 20) design having a 3-(q, 5, 10) design in the resolution.

Corollary 2.5 shows an interesting example of 4-designs that are 3-resolvable, and point-missing 3-resolvable as well.

# 3 Constructions of t-designs from point-missing (t-1)-resolvable t-designs

Recall that Lemma 2.2 shows a natural connection between point-missing and pencillike *s*-resolvability via the complement action. However, we observe that point-missing (t-1)-resolvable *t*-designs may be used to construct pencil-like (t-1)-resolvable *t*designs which are not related to the complementary connection, as shown in the following theorem.

**Theorem 3.1** Let  $(X, \mathcal{B})$  be a point-missing (t - 1)-resolvable t- $(v, k, \lambda)$  design with (t - 1)- $(v - 1, k, \delta)$  designs in the resolution. Then there is a pencil-like (t - 1)-resolvable t- $(v, k + 1, t\delta + \lambda)$  design  $(X, \mathcal{B}^*)$ . If  $|B \cap B'| \leq k - 2$  for any two distinct blocks  $B, B' \in \mathcal{B}$ , then  $(X, \mathcal{B}^*)$  is simple. Further, if there are two blocks  $B, B' \in \mathcal{B}$  with  $|B \cap B'| = k - 1$ , then the simplicity of  $(X, \mathcal{B}^*)$  depends on the structure of the resolution.

Proof. Let  $X = \{1, \ldots, v\}$ . For  $i \in X$  denote  $(X \setminus \{i\}, \mathcal{B}_i)$  the (t-1)- $(v-1, k, \delta)$  design in the point-missing (t-1)-resolution. Define  $\mathcal{B}_i^* = \{i\} \cup \mathcal{B}_i = \{\{i\} \cup B \mid B \in \mathcal{B}_i\}$ , for  $i = 1, \ldots, v$ , and  $\mathcal{B}^* = \bigcup_{i \in X} \mathcal{B}_i^*$ . We claim that  $(X, \mathcal{B}^*)$  is a pencil-like (t-1)-resolvable t- $(v, k+1, t\delta + \lambda)$  design. Let  $T = \{i_1, \ldots, i_t\} \subseteq X$ . Consider a resolution class  $\mathcal{B}_j$  with  $j \in T$ . Since  $(X \setminus \{j\}, \mathcal{B}_j)$  is a (t-1)- $(v-1, k, \delta)$  design, it follows that  $\{i_1, \ldots, i_t\} \setminus \{j\}$  is contained in  $\delta$  blocks of  $\mathcal{B}_j$ . Therefore  $\{j\} \cup \{i_1, \ldots, i_t\} \setminus \{j\} = \{i_1, \ldots, i_t\}$  is contained in  $\delta$  blocks of  $\mathcal{B}_j^*$ . Thus  $\mathcal{B}_{i_1}^*, \ldots, \mathcal{B}_{i_t}^*$  together have  $t\delta$  blocks containing T. Further, the (v-t) resolution classes  $\mathcal{B}_j$  with  $j \notin T$  have  $\lambda$  blocks containing T. It follows that  $(X, \mathcal{B}^*)$  is a t- $(v, k+1, t\delta + \lambda)$  design. Assume that

 $|B \cap B'| \leq k-2$  for any two distinct blocks  $B, B' \in \mathcal{B}$ . Let  $B^*, B'^* \in \mathcal{B}^*$  be the two corresponding blocks of B and B'. If  $B^*, B'^* \in \mathcal{B}^*_i$ , then  $B^* = \{i\} \cup B$  and  $B'^* = \{i\} \cup B'$ , so  $B^* \neq B'^*$ , since  $B \neq B'$ . The other case is that  $B^* \in \mathcal{B}^*_i$  and  $B'^* \in \mathcal{B}^*_j$  for  $i \neq j$ , thus  $B^* = \{i\} \cup B, B'^* = \{j\} \cup B'$ , where  $B \in \mathcal{B}_i$  and  $B' \in \mathcal{B}'_j$ . Since  $|B \cap B'| \leq k-2$ , we have  $B^* \neq B'^*$ . Thus  $(X, \mathcal{B}^*)$  is simple.

The next theorem may be viewed as the reverse of Theorem 3.1.

**Theorem 3.2** Let  $(X, \mathcal{B})$  be a pencil-like (t - 1)-resolvable  $t \cdot (v, k, \lambda)$  design with  $(t-1) \cdot (v-1, k-1, \delta)$  designs in the resolution. Then there is a point-missing (t-1)-resolvable  $t \cdot (v, k - 1, \lambda - t\delta)$  design  $(X, \mathcal{B}^*)$ . If  $|B \cap B'| \leq k - 2$  for any two distinct blocks  $B, B' \in \mathcal{B}$ , then  $(X, \mathcal{B}^*)$  is simple. Further, if there are two blocks  $B, B' \in \mathcal{B}$  with  $|B \cap B'| = k - 1$ , then the simplicity of  $(X, \mathcal{B}^*)$  depends on the structure of the pencil-like (t-1)-resolution.

Proof. Let  $X = \{1, \ldots, v\}$ . For  $i \in X$  denote  $(X \setminus \{i\}, \mathcal{B}_i)$  the (t-1)- $(v-1, k-1, \delta)$  design in the pencil-like (t-1)-resolution of  $(X, \mathcal{B})$ . We have  $\mathcal{B} = (\{1\} \cup \mathcal{B}_1) \cup \cdots \cup (\{v\} \cup \mathcal{B}_v)$  Define  $\mathcal{B}^* = \mathcal{B}_1 \cup \cdots \cup \mathcal{B}_v$ . We claim that  $(X, \mathcal{B}^*)$  is a t- $(v, k-1, \lambda - t\delta)$  design, which is point-missing (t-1)-resolvable. Let  $T = \{i_1, \ldots, i_t\} \subseteq X$ . Then T is contained in  $\lambda$  blocks of  $(X, \mathcal{B})$ , which are distributed in v classes of the pencillike (t-1)-resolution. Note that T is contained in  $\delta$  blocks of  $(\{i_1\} \cup \mathcal{B}_{i_1}),$  for  $i_j \in T$ , so T is contained in  $t\delta$  blocks of  $(\{i_1\} \cup \mathcal{B}_{i_1}) \cup \cdots \cup (\{i_t\} \cup \mathcal{B}_{i_t})$  (i.e., T is not contained in any block of  $\mathcal{B}_{i_1} \cup \cdots \cup \mathcal{B}_{i_t}$ ). The remaining (v-t) classes  $\{(\{1\} \cup \mathcal{B}_1) \cup \cdots \cup (\{v\} \cup \mathcal{B}_v)\} \setminus \{(\{i_1\} \cup \mathcal{B}_{i_1}) \cup \cdots \cup (\{i_t\} \cup \mathcal{B}_{i_t})\}$  of  $(X, \mathcal{B})$  will have  $\lambda - t\delta$  blocks containing T. Moreover, if T is contained in a block  $\{j\} \cup \mathcal{B} \in (\{j\} \cup \mathcal{B}_j), j \in \{1, \ldots, v\} \setminus T$ , then T is contained in  $\mathcal{B} \in \mathcal{B}_j$ . Hence,  $\mathcal{B}_1 \cup \cdots \cup \mathcal{B}_v$  will have  $\lambda - t\delta$  blocks containing T and  $(X, \mathcal{B}^*)$  is point-missing (t-1)-resolvable. Assume that  $|\mathcal{B} \cap \mathcal{B}'| \leq k-2$  for any two distinct blocks  $\mathcal{B}, \mathcal{B}' \in \mathcal{B}$ . Obviously, the two corresponding blocks  $\mathcal{B}^*, \mathcal{B}'^* \in \mathcal{B}^*$  are distinct. Thus  $(X, \mathcal{B}^*)$  is simple.

The simplicity of  $(X, \mathcal{B}^*)$  in Theorem 3.1 in the case that there are two blocks  $B, B' \in \mathcal{B}$  with  $|B \cap B'| = k - 1$  remains a main open question. In fact, examples for simple as well as non-simple  $(X, \mathcal{B}^*)$  do exist in this case. We illustrate the situation with two explicit examples. First, consider the unique Steiner 3-(8, 4, 1) design  $(X, \mathcal{B})$ . By applying Lemma 2.2 we have

Thus the block set  $\mathcal{D} = \bigcup_{x \in X} \mathcal{B}_x$  is the union of derived designs of  $(X, \mathcal{B})$  at all points of  $X = \{0, 1, 2, 3, 4, 5, 6, 7\}$ . Here  $\mathcal{B}_0, \ldots, \mathcal{B}_7$  form an overlarge set of Steiner 2-(7, 3, 1) designs. It is easy to check that the resulting 3-(8, 4, 4) design  $(X, \mathcal{B}^*)$  is not simple, more precisely each block is repeated 4 times. The second example is chosen from the set of 11 non-isomorphic of overlarge sets for 2-(7, 3, 1) designs [18]. The following representation is taken from [15].

$\mathcal{B}_0'$	=	123	145	167	247	256	346	357
$\mathcal{B}_1'$	=	026	035	047	234	257	367	456
$\mathcal{B}_2'$	=	015	037	046	136	147	345	567
$\mathcal{B}_3'$	=	014	025	067	127	156	246	457
$\mathcal{B}_4'$	=	016	023	057	125	137	267	356
$\mathcal{B}_5'$	=	017	024	036	126	134	237	467
$\mathcal{B}_6'$	=	013	027	045	124	157	235	347
$\mathcal{B}_7'$	=	012	034	056	135	146	236	245

It is straightforward to check that  $(X, \mathcal{B}^{\prime*})$  forms a simple 3-(8, 4, 4) design.

The examples indicate an involved problem of deciding the simplicity of  $(X, \mathcal{B}^*)$ , when  $(X, \mathcal{B})$  has two blocks B and B' with  $|B \cap B'| = k - 1$ . The most interesting case for this situation, as mentioned in Theorem 2.3, is overlarge sets of disjoint Steiner (t-1)-(v, t, 1) designs, i.e. the complete t-(v + 1, t, 1) design is point-missing (t-1)resolvable having Steiner (t-1)-(v, t, 1) designs in the resolution classes. Teirlinck [23] has shown that overlarge sets for Steiner 3- $(3^n-1, 4, 1)$  and 3- $(3^n+1, 4, 1)$  designs for  $n \ge 2$  exist, including the known overlarge sets of Steiner 3- $(2^n, 4, 1)$  designs. By using these results we obtain the following infinite series of 4-designs with constant index as a corollary of Theorem 3.1.

**Corollary 3.3** There exist infinite series of pencil-like 3-resolvable 4-designs with the following parameters:

- 1.  $4 (2^n + 1, 5, 5)$  for  $n \ge 2$ ,
- 2. 4-(3<sup>n</sup>, 5, 5) for  $n \ge 2$ ,
- 3.  $4 \cdot (3^n + 2, 5, 5)$  for  $n \ge 2$ .

**Remark 3.1** It should be remarked that for all the designs in Corollary 3.3 we have  $\lambda_{\min} = 1$  or 5. More precisely,

$$\lambda_{\min} = 5 \begin{cases} \text{for } v = 2^n + 1, & \text{and } n \equiv 3 \pmod{4}, \\ \text{for } v = 3^n, & \text{and } n \equiv 2 \pmod{4}, \\ \text{for } v = 3^n + 2, & \text{and } n \equiv 3 \pmod{4}. \end{cases}$$

Note that Alltop [1] has constructed infinite series of simple  $4-(2^n+1, 5, 5)$  designs for n odd and  $n \ge 5$ ; thus the first series extends the point number to all possible values of n.

It is very likely that many non-isomorphic series of 4-designs with parameters given in Corollary 3.3 will exist, which are simple as well as non-simple, due to the fact that the number of non-isomorphic overlarge sets of 3-(v, 4, 1) will strongly increase as v is getting large. In particular, it is important to decide whether the 4-designs in Corollary 3.3 are simple or not. As an observation we take a close look at the first design in each of the 4- $(3^n, 5, 5)$  and 4- $(3^n + 2, 5, 5)$  series. These are 4-(9, 5, 5)and 4-(11, 5, 5) designs, corresponding to n = 2. Note that each 4-(9, 5, 5) design is simple, since its complement is the complete 4-(9, 4, 1) design (otherwise, we would have a non-simple 4-(9, 4, 1) design, which is impossible). In fact, this can also be verified directly by checking the two non-isomorphic overlarge sets of 3-(8, 4, 1) designs given in [9], yielding 4-(9, 5, 5) designs. Note also that 4-(9, 5, 5) is the parameters of the second design in the 4- $(2^n + 1, 5, 5)$  series. The case of 4-(11, 5, 5) designs is quite different. We have inspected the complete list of 21 non-isomorphic overlage sets of 3-(10, 4, 1) designs as shown in [20] and found that they all yield non-simple 4-(11, 5, 5) designs.

For the ease of the reader, we include a table of known infinite series of t-designs with constant index for  $t \ge 4$ .

No.	$t$ - $(v, k, \lambda)$	Conditions	(Non-)Simplicity	References
1	$4 - (2^n + 1, 5, 5)$	$n \ge 5 \text{ odd}$	$\operatorname{simple}$	[1]
2	$4 - (4^n + 1, 5, 2)$	$n \ge 2$	non-simple	[3]
3	$4 - (2^n + 1, 5, 5)$	$n \ge 4$	?	Cor.3.3
4	$4 - (3^n, 5, 5)$	$n \ge 3$	?	Cor.3.3
5	$4 - (3^n + 2, 5, 5)$	$n \ge 3$	?	Cor.3.3
6	$4 - (2^n + 1, 5, \lambda)$	$\lambda \in \{20, 25\}, \operatorname{gcd}(n, 6) = 1$	$\operatorname{simple}$	Cor.2.5, [8]
7	4-(60u+4,5,60)	gcd(u, 60) = 1  or  2	simple	[22]
8	$4 - (2^n + 1, 6, 10)$	$n \ge 5 \text{ odd}$	simple	[5]
9	$4 - (2^n + 1, 6, \lambda)$	$\lambda \in \{60, 70, 90, 100, 150, 160\},\$	simple	[4]
		gcd(n,6) = 1		
10	$4 - (2^n + 1, 8, 35)$	gcd(n,6) = 1	simple	[4]
11	$4 - (2^n + 1, 9, \lambda)$	$\lambda \in \{84, 63, 147\}, \gcd(n, 6) = 1$	$\operatorname{simple}$	[6, 4]
12	$5 - (2^n + 2, 6, 15)$	$n \ge 3$	non-simple	[11]
13	$5 - (2^n, 6, 3)$	$n \ge 3$	non-simple	[7]
14	$7-(2^n, 8, 45)$	$n \ge 6$	non-simple	[7]
15	$t - (v, t + 1, (t + 1)!^{2t+1})$	$v \equiv t \pmod{(t+1)!^{2t+1}}$	simple	
		$v \ge t+1$		[21]

**Table 1:** Known infinite series of t-designs with constant index for  $t \ge 4$ 

**Theorem 3.4** There exists a pencil-like 3-resolvable  $4 \cdot (2^n + 1, 7, \frac{70}{3}(2^n - 5))$  design for  $n \ge 5$  and gcd(n, 6) = 1.

Proof. Each 4- $(2^n + 1, 6, 10)$  design  $(X, \mathcal{B})$  with  $n \ge 5$  and gcd(n, 6) = 1 in [8] has the property that  $|B \cap B'| \le 4$  for any two distinct blocks  $B, B' \in \mathcal{B}$ . Its complement is a 4- $(2^n+1, 2^n-5, \frac{2}{3}\binom{2^n-5}{4})$  design  $(X, \bar{\mathcal{B}})$  having block intersections at most  $(2^n-3)$ . By Theorem 2.3 there is a point-missing 3-resolvable 4- $(2^n+1, 2^n-6, (2^n-9)\frac{2}{3}\binom{2^n-5}{4}))$ design  $(X, \bar{\mathcal{D}})$ . Again, the complement of  $(X, \bar{\mathcal{D}})$  is pencil-like 3-resolvable 4- $(2^n + 1, 7, \frac{70}{3}(2^n - 5))$  design, as desired.

By applying Theorem 3.2 to the point-missing 3-resolvable  $4 \cdot (2^n + 1, 2^{n-1}, (2^{n-1} - 3)(2^{n-2} - 1))$  design  $(X, \mathcal{B})$  of Alltop [2], we obtain an interesting result. Namely, we prove that there is a point-missing 3-resolvable design  $(X, \mathcal{B}^*)$  with the same parameters as  $(X, \mathcal{B})$  and disjoint from  $(X, \mathcal{B})$  (recall that any two distinct blocks  $B, B' \in \mathcal{B}$  have  $|B \cap B'| \leq 2^{n-1} - 2$ ). Let  $\mathcal{B} = \mathcal{B}_1 \cup \cdots \cup \mathcal{B}_v$  be a partition of  $\mathcal{B}$  into point-missing 3-resolution classes, i.e. each  $(X_i, \mathcal{B}_i)$  is a  $3 \cdot (2^n, 2^{n-1}, 2^{n-2} - 1)$  design with  $X_i = X \setminus \{i\}$ . Consider  $(X, \overline{\mathcal{B}})$  as the complement of  $(X, \mathcal{B})$ . So,  $(X, \overline{\mathcal{B}})$  has parameters  $4 \cdot (2^n + 1, 2^{n-1} + 1, (2^{n-1} + 1)(2^{n-2} - 1))$  and is pencil-like 3-resolvable. Here,  $\overline{\mathcal{B}} = (\{1\} \cup \widetilde{\mathcal{B}}_1) \cup \cdots \cup (\{v\} \cup \widetilde{\mathcal{B}}_v)$ , where  $\widetilde{\mathcal{B}}_j$  is the complement of  $\mathcal{B}_j$  in  $X_j$ , and  $(X_j, \widetilde{\mathcal{B}}_j)$  is a  $3 \cdot (2^n, 2^{n-1}, 2^{n-2} - 1)$  design, for  $j = 1, \ldots, v$ . The proof of Theorem 3.2 shows that  $(X, \widetilde{\mathcal{B}^*})$  with  $\widetilde{\mathcal{B}^*} = \widetilde{\mathcal{B}}_1 \cup \cdots \cup \widetilde{\mathcal{B}}_v$ , is point-missing 3-resolvable with  $(X_j, \widetilde{\mathcal{B}}_j)$  as the design in the resolution. Clearly,  $(X, \mathcal{B})$  and  $(X, \widetilde{\mathcal{B}^*})$  are disjoint and they have the same parameters. Further, the 4-design  $(X, \mathcal{B} \cup \widetilde{\mathcal{B}^*})$  can be extended to a 5-design. Thus we have the following theorem.

**Theorem 3.5** Let  $n \ge 4$ . Then

- 1. there exists a simple point-missing 3-resovable  $4-(2^n+1, 2^{n-1}, 2(2^{n-1}-3)(2^{n-2}-1))$  design,
- 2. there exists a simple  $5 \cdot (2^n + 2, 2^{n-1} + 1, 2(2^{n-1} 3)(2^{n-2} 1))$  design.

## 4 A construction of point-missing *s*-resolvable *t*designs

In this section we show that the recursive construction of t-designs in [24] can be extended to a construction of point-missing s-resolvable t-designs. More precisely, we prove the following theorem.

**Theorem 4.1** Assume that there exists a point-missing s-resolvable t- $(v, k, \lambda)$  design having s- $(v-1, k, \delta)$  designs in its resolution. If  $v\lambda_0(\lambda_0 - \lambda_1) < \binom{v}{k}$ , then there exists a point-missing s-resolvable t- $(v + 1, k, (v + 1 - t)\lambda)$  design having s- $(v, k, (v - s)\delta)$  designs in its resolution.

*Proof.* Assume that  $(Y, \mathcal{D})$  is a point-missing *s*-resolvable t- $(v, k, \lambda)$  design. Let  $X = \{1, \ldots, v+1\}$  and denote  $X_j = X \setminus \{j\}$  for  $j = 1, \ldots, v+1$ . Let  $(X_j, \mathcal{B}^{(j)})$  be a copy of  $(Y, \mathcal{D})$  defined on  $X_j$ . If  $v\lambda_0(\lambda_0 - \lambda_1) < {v \choose k}$ , then by Theorem A in [24] there

are (v+1) mutually disjoint  $\mathcal{B}^{(1)}, \ldots, \mathcal{B}^{(v+1)}$  and they form a t- $(v+1, k, (v+1-t)\lambda)$  design  $(X, \mathcal{B})$ , where

$$\mathcal{B} = \bigcup_{j=1}^{v+1} \mathcal{B}^{(j)}.$$

We prove that  $(X, \mathcal{B})$  is point-missing *s*-resolvable. Denote the partition of  $(X_j, \mathcal{B}^{(j)})$  into point-missing *s*-resolution classes by

$$\mathcal{B}^{(j)} = \overbrace{\mathcal{C}_1^{(j)} \cup \cdots \cup \mathcal{C}_{j-1}^{(j)} \cup \mathcal{C}_{j+1}^{(j)} \cup \cdots \cup \mathcal{C}_{v+1}^{(j)}}^{v},$$

with  $(X_{i,j}, \mathcal{C}_i^{(j)})$  as an s- $(v - 1, k, \delta)$  design, where  $X_{i,j} = X_j \setminus \{i\}$  and  $i \in X_j$ . For each point  $j \in X$  define

$$\mathcal{C}_j = \overbrace{\mathcal{C}_j^{(1)} \cup \mathcal{C}_j^{(2)} \cup \cdots \cup \mathcal{C}_j^{(j-1)} \cup \mathcal{C}_j^{(j+1)} \cup \cdots \cup \mathcal{C}_j^{(v+1)}}^v.$$

We claim that  $(X_j, \mathcal{C}_j)$  is an s- $(v, k, (v-s)\delta)$  design. Let  $S = \{j_1, \ldots, j_s\} \subseteq X_j$ . Then S will not appear in the blocks of  $\mathcal{C}_j^{(j_1)}, \mathcal{C}_j^{(j_2)}, \ldots, \mathcal{C}_j^{(j_s)}$ . Hence S appears in (v-s) block sets  $\mathcal{C}_j^{(i)}$ , for  $i \neq j_1, \ldots, j_s$ . In other words, S is contained in the blocks of  $\mathcal{C}_j$  exactly  $(v-s)\delta$  times, which proves the claim. Further, since

$$\mathcal{B} = \mathcal{C}_1 \cup \cdots \cup \mathcal{C}_{v+1}$$

 $(X, \mathcal{B})$  is point-missing s-resolvable with  $\mathcal{C}_1, \ldots, \mathcal{C}_{v+1}$  as resolution classes. Note that the value of  $\delta$  can be computed in terms of  $t, v, k, \lambda$  by using Lemma 2.1.

As an application of Theorem 4.1 consider the infinite series of 4-designs  $(X, \mathcal{D})$  constructed by Alltop in [2].  $(X, \mathcal{D})$  has parameters  $4 \cdot (2^n + 1, 2^{n-1}, (2^{n-1} - 3)(2^{n-2} - 1))$ ,  $n \geq 4$ , and is point-missing 3-resolvable with  $3 \cdot (2^n, 2^{n-1}, 2^{n-2} - 1)$  designs in its resolution. For  $n \geq 5$  the condition  $v\lambda_0(\lambda_0 - \lambda_1) < {v \choose k}$  is satisfied, therefore Theorem 4.1 gives the following corollary.

**Corollary 4.2** For  $n \ge 5$ , there exists an infinite series of simple point-missing 3-resolvable  $4 \cdot (2^n + 2, 2^{n-1}, (2^n - 2)(2^{n-1} - 3)(2^{n-2} - 1))$  designs. The parameters of the 3-designs in the resolution are  $3 \cdot (2^n + 1, 2^{n-1}, (2^n - 2)(2^{n-2} - 1))$ .

#### 5 Conclusion

The paper deals with point-missing s-resolvable t-designs with emphasis on their use in constructing t-designs. Among others, we show the existence of infinite series of 4-(v, 5, 5) designs with  $v = 2^n + 1$ ,  $3^n$ ,  $3^n + 2$  for  $n \ge 2$ . It remains an open question about the simplicity of the designs in these series. We also present a recursive construction of point-missing s-resolvable t-designs including an application.

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