Course "Modelling of Concurrent Systems" Summer Semester 2019 University of Duisburg-Essen

Harsh Beohar LF 265, harsh.beohar@uni-due.de

Course handler

Harsh Beohar

- Room I F 265
- E-Mail: harsh.beohar@uni-due.de
- Meeting by appointment.
- Please send mail only by your official student mail id's.

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http://www.uni-due.de/zim/services/e-mail/
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Task: Lecturer + Exercise Tutor.

Website: https:

//www.uni-due.de/theoinf/teaching/ss2019_modns.php

Lecture schedule

Schedule:

- Tuesday, 14:15-15:30, in Room LF 035
- Friday, 12:15-13:30, in Room LF 035

Exercises

Schedule:

(Roughly, every fourth lecture kept for exercises.)

- Tuesday, 30/04, 14:15-15:30, in Room LF 035.
- Tuesday, 14/05, 14:15-15:30, in Room LF 035.
- Tuesday, 28/05, 14:15-15:30, in Room LF 035.
- Friday, 14/06, 12:15-13:30, in Room LF 035.
- Yet to be decided.

Idea:

- Problem sheet will be announced in the class, whenever it is published.
- At the same time, also the deadline to submit the exercises will also be announced.
- Submission: in person or email. Please use Matriculation number and sheet number.

Exercises

Scheme:

- If the sum is more than 60% then you get a bonus point.
- Effect is improvement by one grade level. E.g. 2.3 to 2.0
- Group solutions are not allowed.

Target audience

MAI

Master "Applied computer science" ("Angewandte Informatik") - focus engineering or media computer science:

 In the brochure you can find the field of application: "Distributed Reliable Systems" ("Verteilte, Verlässliche Systeme")

Concurrent systems (Nebenläufige Systeme)

Stundenzahl: $4 SWS (3V + 1\ddot{U})$, 6 Credits

Target audience

Master ISE/CE – Verteilte, Verlässliche Systeme

In Master "ISE – Computer Engineering", this lecture is classified as follows:

 Elective "Verteilte, Verlässliche Systeme" (Reliable Systems)
 Stundenzahl: 4 SWS (3V + 1Ü)

Requirement

Prerequisites:

- Automata and Formal languages.
- Logic.

For the past teaching content, see

http://www.ti.inf.uni-due.de/teaching/ss2018/mod-ns/

Examination

The exam will be held as a viva voce (oral examination).

Planned dates:

18th July 2019 (Thursday) and 19th July 2019 (Friday).

Literature

Jos Baeten, Twan Basten, and Michel Reniers.

Process algebra: Equational theories of communicating processes Cambridge University Press, 2010.

Contents: (Probabilistic) Process algebra.

Luca Aceto, Anna Ingólfsdóttir, Kim G. Larsen, Jiri Srba.
 Reactive Systems: Modelling, Specification and Verification.
 Cambridge University Press, 2007.

Contents: Strong and weak bisimulation, Hennessy-Milner logic, Timed automata

Rob van Glabbeek.

Behavioural equivalences. The linear time - branching time spectrum I. In proc. of CONCUR 90.

Contents: Failure equivalence, (bi)simulation equivalence

Literature in Process algebra

Robin Milner.

Communication and Concurrency. Prentice Hall, 1989.

Contents: Process calculus (CCS), Strong and weak bisimulation, Hennessy-Milner logic.

Tony Hoare.

Communicating sequential processes 2004. Available at http://www.usingcsp.com/cspbook.pdf

Contents: Process calculus CSP, Failure equivalence

Bill Roscoe.

The Theory and Practice of Concurrency 1997. Available at

http://www.cs.ox.ac.uk/people/bill.roscoe/publications/68b.pdf.

Contents: A reference book on CSP



Literature in Hybrid systems

- Hybrid process algebra by Pieter Cuijpers.
 Elsevier journal article or PhD thesis under the same name.
 Contents: Hybrid transition systems, hybrid process algebra, stateless bisimulation
- André Platzer.

Logical foundations of Cyber-Physical Systems. Springer, 2018.

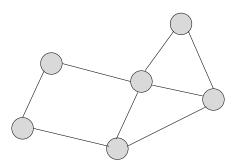
Contents: Semantics of differential equations, differential logic.

Lecture style

- We will follow "the" process algebra book. Also, which sections are to be read for the next lecture will be announced in the current one.
- Very few materials will be presented using slides and mostly on blackboard. So please make your own notes!
- However, for hybrid systems there will be lecture notes.

What are concurrent systems?

In general: systems in which several components/processes run concurrently and typically communicate via message passing.



Concurrency versus parallelism:

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Parallelism

Two events take place in parallel if they are executed at the same moment in time.

Concurrency

Two events are concurrent if they *could potentially* be executed in parallel, but they do not have to. This means there is no causal dependency between them.

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Parallelism

Two events take place in parallel if they are executed at the same moment in time.

Concurrency

Two events are concurrent if they *could potentially* be executed in parallel, but they do not have to. This means there is no causal dependency between them.

Hence: concurrency is the more general term.

Examples?

(Potential) characteristics of concurrent systems

- Concurrency/parallelism
- Openness (extendability, interaction with the environment)
- Modularity
- Nonterminating behaviour (infinite runs)
- Nondeterminism
- Temporal properties (e.g. "an event will occur eventually")

Problems with concurrent systems

- Deadlocks
- Guaranteeing mutual exclusion
- Infinite respectively huge state space
- Strongly dynamic behaviour/changing number of processes
- Variable topology/mobility

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Hence: We need methods to model, analyze and verify such systems.

- Program is a function that transform an input into output.
- Two programs are equivalent if and only if they compute the same output for every input.

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- **1** x = 1;
- ② x = x + 1;
- print x;

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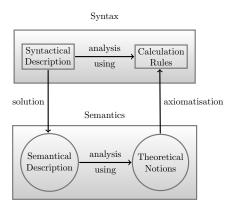
$$x = x \times 2$$

Mathematical modelling

- Inspired from traditional engineering disciplines.
- Make system models in formal way.
- Analyse them.
- Then build the 'real' system and test it against those models.

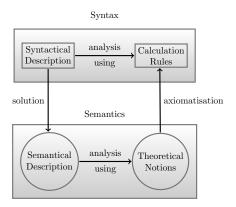
Mathematical modelling (Cuijpers 2004.)

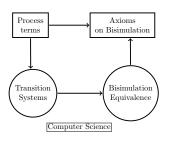
Syntax aims at concise and finite way of handling semantical notions, which can be infinite mathematical objects.



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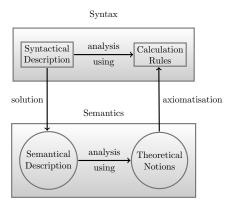
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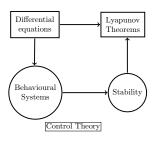


Table of contents

We will introduce the following models for concurrent systems:

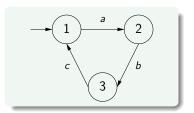
- Transition systems
- Models which are closer to realistic programming languages (for instance process calculi)
- Additional models: Hybrid transition systems.

Furthermore (in order to investigate/analyze systems):

- Specification of properties of concurrent systems (Hennessy-Milner logics)
- Behavioural equivalences: When do two systems behave the same (from the point of view of an external observer)?

Transition systems

- Transition systems represent states and transitions between states.
- True parallelism is not directly represented.
- Strong similarity to automata, however we are here not so much interested in the accepted language.



- For a set X, we write X^* for the set of all finite words including the empty one ε .
- For a set X, we write X^{ω} the set of all infinite words. Also, we write $X^{\infty} = X^* \cup X^{\omega}$.
- A binary relation R between the sets X and Y is a subset of $X \times Y$. i.e., $R \subseteq X \times Y$.
- Often, we write xRy iff $(x, y) \in R$.
- A preorder $R \subseteq X \times Y$ is a

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- A partial order (poset) R is a preorder that is antisymmetric.
- An equivalence relation R is a partial order that is symmetric.

Transition system space

Formal definition

A transition system space is a triple (S, L, \rightarrow) of

- lacktriangledown a set of states S;
- 2 a set of labels L;
- **3** a transition relation $\rightarrow \subseteq S \times L \times S$;

Notations:

- $s \xrightarrow{a} t \iff (s, a, t) \in \rightarrow$
- $s \stackrel{a}{\rightarrow} \iff \nexists_{t \in S} s \stackrel{a}{\rightarrow} t$

Basics

Example on board.

Definition

The reachability relation $\multimap \subseteq S \times L^* \times S$ is inductively defined as follows:

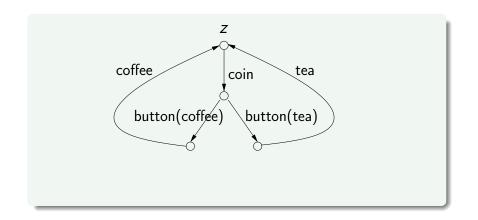
$$\frac{\varepsilon}{s \overset{\varepsilon}{\to} s} \qquad \frac{s \overset{w}{\to} s' \ s' \overset{a}{\to} s''}{s \overset{wa}{\to} s''}$$

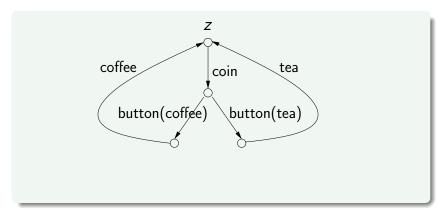
The transition system induced by state s consists of all states reachable from s, and it has the transitions and final states induced by the transition system space.

A classical example: the tea/coffee-machine

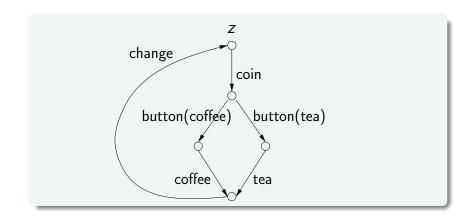
We want to model a very simple machine that

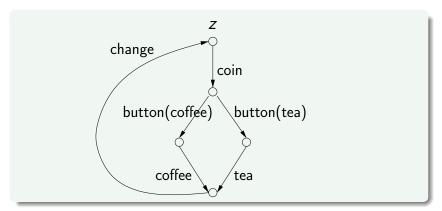
- outputs tea or coffee after a coin has been inserted and a button has been pressed,
- can show faulty behaviour and
- may potentially behave non-deterministically.



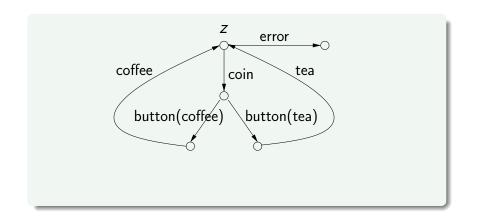


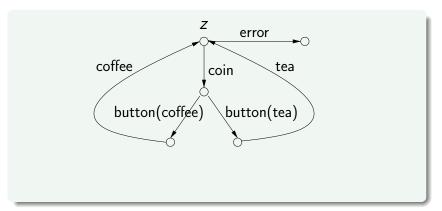
A tea/coffee-machine.



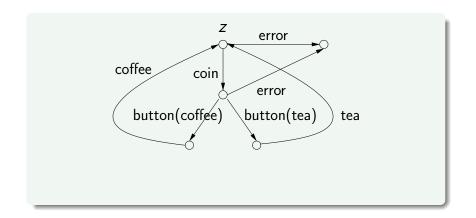


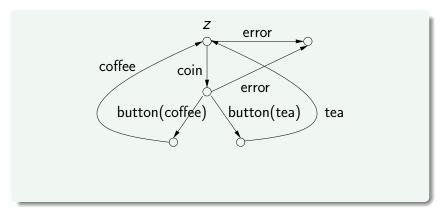
A machine that gives back change.



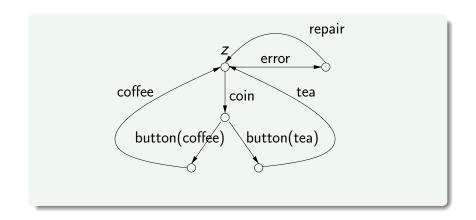


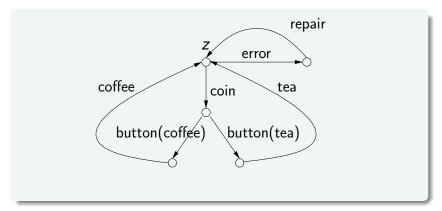
A machine with an error. The occurrence of an error is actually rather an internal action and could alternatively be modelled with a τ .



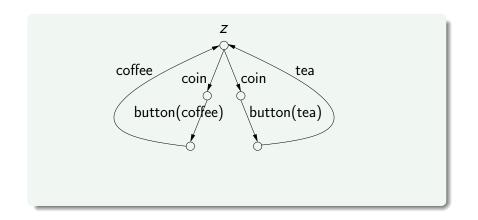


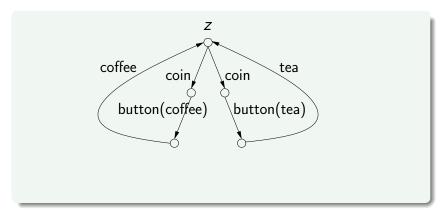
An (unfair) machine with faulty behaviour which may enter the error state after a coin has been inserted.





A machine with an error state that can be repaired.





A machine with non-deterministic behaviour that makes a choice of beverages for the user.

Deterministic transition systems

Deterministic transition system (definition)

A state s of a transition system is deterministic

$$\forall_{s',s''\in S,a\in L} (s\stackrel{a}{\rightarrow}s'\wedge s\stackrel{a}{\rightarrow}s'') \implies s'=s''$$

A transition system induced by state s is deterministic if every reachable states from s is deterministic.

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Remarks:

• All tea/coffee-machines, apart from the last, are deterministic.

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Remarks:

- All tea/coffee-machines, apart from the last, are deterministic.
- Opposed to deterministic finite automata we do not require for deterministic transition systems that every action is feasible in every state.

Some more definitions

• A state s of a transition system is a deadlock state iff

$$\forall_{a \in L} \not\equiv_t s \xrightarrow{a} t.$$

A transition system starting from s has a deadlock iff a deadlock state is reachable from s.

- A transition system is regular iff both its set of states and transitions are finite
- A transition system is *image finite* iff each of its states has only finitely many outgoing transitions.