

Robotics & Autonomous Driving Systems

20. July 2021 / 12:15-15:30h



Learn about the design of industrial robots and the development of autonomous driving systems with MATLAB & Simulink.

[Register here](#)

Highlights

- Co-simulation of Simulink with Gazebo and Unreal Engine
- Create 3D scenes with RoadRunner
- Path planning with obstacle avoidance

AGENDA

12:15-13:30h

[Part 1: How to design industrial robots with MATLAB & Simulink](#)

- Introduction to applying MATLAB & Simulink in autonomous systems workflows
- Case study: Pick and place manipulation application
 - Perception algorithm using Deep Learning
 - Supervisory logic and control using Stateflow & Reinforcement Learning
 - ROS node generation

13:45-15:30h

[Part 2: Autonomous driving systems development with MATLAB & Simulink](#)

- What's new in MATLAB & Simulink for autonomous driving
 - Driving scenarios – analysis and simulation
 - Algorithms for perception, planning and control
 - Integration and testing of autonomous driving systems
- Case study: Highway lane change & highway lane following application

Who should attend: This seminar is designed for graduate students in the field of robotics and automotive systems at the University Alliance Ruhr